Supplementary Material

AlphaGrad: Normalized Gradient Descent for Adaptive Multi-loss Functions in EEG-based Motor Imagery Classification

Rattanaphon Chaisaen^[b], Phairot Autthasan^[b], Apiwat Ditthapron^[b], and Theerawit Wilaiprasitporn^[b] Senior Member, IEEE

¹Bio-inspired Robotics and Neural Engineering (BRAIN) Lab, School of Information Science and Technology (IST), Vidyasirimedhi Institute of Science and Technology (VISTEC), Rayong, Thailand

²Department of Innovation Information Systems, Faculty of Business Administration, Rajamangala University of Technology Krungthep, Bangkok, Thailand

Corresponding authors Apiwat Ditthapron (e-mail: apiwat.d@mail.rmutk.ac.th), and Theerawit Wilaiprasitporn (e-mail: theerawit.w@vistec.ac.th)

S1 Multi-Task Learning-Based MI-EEG Classification Architecture

We implemented MIN2Net [1] and FBMSNet [2] based on the descriptions provided in their respective publications. One notable modification made to MIN2Net (our previous work) is the migration from the TensorFlow framework to PyTorch. In this transition, we introduced minor changes to the decoder layers to align with Py-Torch's implementation standards. The design philosophies of both models are discussed in Section II (Related Work) of the main manuscript. Here, we provide implementation-level details of MIN2Net in Table S1 and FBMSNet in Table S2. Additionally, the model complexity, including comparisons with single-task state-ofthe-art baseline models, is summarized in Table S3. The complete source code and implementation used in our experiments are available at: https://AlphaGrad.github.io.

Block	Layer	Filter	Size	Stride	Activation	Options	Output
	Input Conv2D Activation	С	(C,T,1) (64,1)	1	ELU	padding=same	(C,T,1) (C,T,1)
Encoder	BatchNorm2D AvgPool2D Conv2D	<i>C</i> //2	(T//FS, 1) (32, 1)	1		padding=same	(C, T, 1) (C, FS, 1) (C//2, FS, 1)
	Activation BatchNorm2D AvgPool2D Flatten		(4,1)		ELU		(C//2, FS, 1) (C//2, FS//4, 1) (C//2) * (T//(T//FS))//4
Latent	FC		(z)				(z)
Decoder	FC Unflatten Conv2D Upsampling2D Activation	<i>C</i> //2	$(z) \\ (C//2, FS//4, 1) \\ (64, 1) \\ (FS, 1)$	4	ELU	dim=1 padding=same	$\begin{array}{c} (C//2)*(FS//4)\\ (C//2,FS//4,1)\\ (C//2,FS//4,1)\\ (C//2,FS,1) \end{array}$
	Conv2D Upsampling2D Activation		(32,1) (<i>T</i> ,1)		ELU	padding=same	(C, FS, 1) (C, T, 1)
Supervised Learning	Latent FC	N _c			Softmax		$(z) \\ (N_c)$

Table S1	: MIN2Net	architecture.
----------	-----------	---------------

C is number of EEG channels, T is number of time points, FS is EEG sampling rate, z is latent size, and Nc is number of output classes.

Table S2:	FBMSNet	architecture.
-----------	---------	---------------

Block	Layer	Filter	Size	Stride	Activation	Options	Output
	Input		(N_b, C, T)				(N_b, C, T)
	Conv2D	9	(1,15)	1	Linear	padding=same	(9, C, T)
Filtering	Conv2D	9	(1,31)	1	Linear	padding=same	(9, C, T)
	Conv2D	9	(1,63)	1	Linear	padding=same	(9, C, T)
	Conv2D	9	(1,125)	1	Linear	padding=same	(9, C, T)
	Concatenate					dim=1	(36, C, T)
	BatchNorm						(36, C, T)
	DepthwiseConv2D	288	(C, 1)	1	Linear	group=36	(228, 1, T)
Feature Extraction	BatchNorm						(228, 1, T)
	Activation				swish		(228, 1, T)
	Reshape						(228, T//w, w)
	Variance		(w)				(228, T//w, 1)
Latant	Flatten						(228 * (T//w))
Latent	FC		(228 * (T//w))				(228 * (T//w))
Supervised Learning	FC	N _c			LogSoftmax		(N_c)

C is number of EEG channels, T is number of time points, Nb is the number of frequency bands, w is the window length of variance layer, and Nc is number of output classes.

S2 Model Complexity

To evaluate the real-time feasibility of the resulting MTL networks (MIN2Net and FBMSNet) in comparison with single-task deep learning models commonly used for EEG-based BCIs, we assessed both architectural complexity (in terms of total trainable parameters) and inference time, including the preprocessing step of bandpass filtering. Table S3 summarizes the number of filtering bands, total trainable parameters, and the average inference time per sample for each model. Importantly, the reported inference time includes the band-pass filtering step, thereby providing a realistic estimate of the end-to-end latency in practical BCI systems. The low latency observed in both MTL models indicates their viability for real-time applications, where fast and accurate decoding is critical for user feedback.

Model	#Filtring Bands	Total Parameters	Inference time (ms/sample)
DeepConvNet	1	153,427	3.8925 ± 0.5336
EEGNet	1	4,402	$\begin{array}{c} 2.9769 \pm 0.5393 \\ 13.3224 \pm 3.0026 \end{array}$
FBCNet	9	8,930	
MIN2Net	1	55,232	$\begin{array}{c} 3.8065 \pm 0.5934 \\ 10.5056 \pm 1.5961 \end{array}$
FBMSNet	9	13,349	

Table S3: M	odel Complexity.
-------------	------------------

References

- [1] P. Autthasan, R. Chaisaen, T. Sudhawiyangkul, P. Rangpong, S. Kiatthaveephong, N. Dilokthanakul, G. Bhakdisongkhram, H. Phan, C. Guan, and T. Wilaiprasitporn, "Min2net: End-to-end multi-task learning for subject-independent motor imagery eeg classification," *IEEE Transactions on Biomedical Engineering*, vol. 69, no. 6, pp. 2105–2118, 2022.
- [2] K. Liu, M. Yang, Z. Yu, G. Wang, and W. Wu, "Fbmsnet: A filter-bank multi-scale convolutional neural network for eeg-based motor imagery decoding," *IEEE Transactions on Biomedical Engineering*, vol. 70, no. 2, pp. 436–445, 2023.